Streamlines

In the "NeraCalc" program, a flow field with cylinder symmetry is calculated, which obeys the following system of (Ideal Flow) equations:

$$\frac{@r:U}{@r} + \frac{@r:V}{@Z} = 0 \qquad ; \qquad \frac{@U}{@Z} - \frac{@V}{@r} = 0$$

Here: r = coordinate in radial direction and z = coordinate in axial direction, u = component of velocity in radial direction and v = component of velocity in axial direction.

A streamline in this flow field is characterized by the fact that the velocity vector is tangent in every point:

$$\frac{dz}{dr} = \frac{v}{u}$$

Suppose that there exists a function in such a way that the streamlines are coincident with the isolines of (r, z). The differential of any such function can be written as:

$$d = \frac{@}{@r}dr + \frac{@}{@z}dz$$

An isoline of f is characterized by the fact that the function does not change when travelling along this line: d = 0.

As a consequence, along an isoline, the following holds:

$$\frac{@}{@r}dr + \frac{@}{@z}dz = 0 \implies \frac{dz}{dr} = -\frac{@}{@} \frac{=@r}{@} = @z$$

But:
$$\frac{dz}{dr} = \frac{v}{u} \quad \text{Hence:} \quad -\frac{@}{@} \frac{=@r}{@} = \frac{v}{u}$$

From which it may be concluded that:

$$\frac{\partial}{\partial r} = :V \qquad ; \qquad \frac{\partial}{\partial Z} = - :U$$

Where the constant is yet to be determined.

It is required, in addition, that the function is a true differentiable and smooth function. To that end, the following equation must hold:

$$\frac{@}{@r}\left(\frac{@}{@Z}\right) = \frac{@}{@Z}\left(\frac{@}{@r}\right)$$

Hence:

$$\frac{@(-:U)}{@r} = \frac{@:V}{@Z} \implies \frac{@:U}{@r} + \frac{@:V}{@Z} = 0$$

Now the flow field, whether Ideal or not, is characterized by the fact that the equation of continuity (conservation of mass) is valid:

$$\frac{@r:U}{@r} + \frac{@r:V}{@Z} = 0$$

It is concluded, therefore, that a sufficient condition is obtained by: = r. From which it is inferred that:

$$\frac{@}{@r} = r:v \quad ; \quad \frac{@}{@z} = -r:u \implies d = r:v:dr - r:u:dz$$

Let's integrate this expression over a certain finite distance, characterized by endpoints (1/2):

$$\int_{1}^{2} d = \int_{1}^{2} r : v : dr - \int_{1}^{2} r : u : dz$$

The radial coordinate r as well as the velocities u and v will vary only linearly over this small distance, thus assuming mean values:

$$_{2} - _{1} = \frac{1}{2}(r_{2}^{2} - r_{1}^{2})v - \frac{1}{2}(r_{1} + r_{2})(z_{2} - z_{1})u$$

An expression which may be simplified as follows:

$$_{2} - _{1} = \frac{1}{2}(r_{2} + r_{1})[(r_{2} - r_{1}):v - (z_{2} - z_{1}):u]$$

This is the final discretization formula, as has been used in the "NeraCalc" program, for calculating the streamline function called $\ .$